

VALIDATION

UNIFIED DISPERSION MODEL

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This report describes the validation of the UDM in its entirety by comparison with measurements from large-scale field experiments.

Reference to part of this report which may lead to misinterpretation is not permissible.

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ABSTRACT

This report describes the validation of the Unified Dispersion Model (UDM).

The UDM theory is described by an accompanying report. The UDM models the dispersion following a ground-level or elevated twophase pressurised release. It effectively consists of the following linked modules: jet dispersion, non-equilibrium droplet evaporation and rainout and touchdown, pool spread and vaporisation, heavy gas dispersion, passive dispersion. The UDM allows for continuous, instantaneous and constant finite-duration releases. The UDM also allows for general time-varying releases. In addition to the nonequilibrium droplet thermodynamics model, UDM also allows for a two-phase HF thermodynamics model (including effects of polymerisation). Another feature of the UDM is possible plume lift-off, where a grounded cloud becomes buoyant and rises into the air. Rising clouds may be constrained to the mixing layer if it is reached.

This report includes a comprehensive description of the overall validation of the UDM model. This includes a description of each validation experiment, the details of the assumptions made for the UDM simulation plus a detailed discussion of the results obtained from a statistical and graphical comparison against the field data.

The UDM verification manual discusses the verification of the individual modules, which includes validation against wind-tunnel experiments. The current document is concerned with the validation of the overall model, which involves validation against the following field experiments:

- Continuous releases: Thorney Island (Freon and Nitrogen), Goldfish (HF), Prairie Grass (passive), Desert Tortoise (Ammonia), FLADIS (Ammonia), EEC (Propane) and Maplin Sands LPG experiments. Various other continuous releases, are included to assess vertical releases into a crosswind: Schatzmann (wind tunnel), Donat (wind tunnel), Vidali (wind tunnel), Li (wind tunnel) and a field experiment by Engie (LNG)
- Instantaneous releases: Thorney Island experiments (Freon and Nitrogen)
- Finite-duration releases: Kit Fox (CO2) and Jack Rabbit II (Chlorine) experiments.
- Buried pipeline ruptures (CO₂) COSHER experiments
- Continuous and time-varying pressurised CO2 experiments carried out at Spadeadam (BP and Shell data made available via CO2PIPETRANS JIP)
- PHMSA validation set: selection of experiments including
	- Dispersion from time-varying pools: Maplin Sands, Burro and Coyote (all LNG)
	- Continuous releases: Thorney Island (Freon and Nitrogen)
	- Wind-tunnel releases: CHRC-A (CO2), BA-Hamburg, BA-TNO (SF6)

The performance of the UDM in predicting peak centreline concentration and cloud widths is found to be overall very good.

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1 INTRODUCTION

A full description of the theory underlying the UDM is described in the accompanying UDM theory manual. The UDM verification manual describes the verification of the individual modules, which were mainly carried out against *windtunnel* data. This report is concerned with the validation of the UDM in its entirety. To this end UDM predictions are compared with measurements from a selection of the available experimental *field* data. The basis and choice of these experiments stem from the model evaluation carried out by Hanna et al^{[10](#page-10-2)}, the EU SMEDIS¹ programme (Scientific Model **E**valuation of **D**ense gas d**is**persion models), and the UDM validation against the experiments in the US PHMSA LNG Model Validation database^{2,3,4}. In addition more recent experiments have been added relating to both unpressurised and pressurised CO₂ releases, as well as for the PHMSA process for approving models for use with LNG in the US.

Chapters 2 and 3 provide full description of the validation sets and details of the methods used within the model to simulate the experimental conditions.

Chapter 4 presents and discusses results from the comparison of the UDM predictions with the measured experimental data.

All experimental simulations in this report can be supplied to licensed users as Phast .psux files.

2 DESCRIPTION OF THE VALIDATION EXPERIMENTS

The validation set consists of 13 sets of field scale experiments and 3 sets of wind tunnel experiments, covering a wide range of release scenarios. This includes continuous, instantaneous, finite-duration and time-varying releases, unpressurised and pressurised releases, and vapour and two-phase releases. A summary of each is provided in Table 1 whilst a more detailed, qualitative description of each experiment is presented below:

- Continuous releases (see Section [4.1;](#page-13-1) excluding $CO₂$ releases)
	- *Prairie Grass* A small quantity of Sulphur dioxide was released at or near ground level over flat terrain. Experiments were carried out during both daylight and non-daylight hours giving rise to a wide range of atmospheric stabilities. Concentrations were measured from an array of sensors located on an arc at downwind distances of 50, 100, 200 400 and 800m.
	- *Desert Tortoise* Liquefied ammonia was released under pressure in the downwind direction through a pipe which was situated approximately 1 m above the ground. At the exit of the pipe, the ammonia flashed to form a two-phase aerosol, a small quantity of which rained out downwind of the release. Concentration measurements were made from an array of sensors located on an arc at downwind distances of 100 and 800m.
	- *EEC* In this experiment pressurised liquid propane was released approximately 0.5 m above the ground to form a two-phase aerosol. Concentrations were measured up to a maximum distance of 64m.
	- *FLADIS* The experiment was designed to investigate the downwind dispersion of an ammonia aerosol. Liquefied ammonia was released under pressure through a nozzle situated at a height of 1.5m. These experiments differed from the Desert Tortoise experiments because the release rates were much lower, allowing for the investigation of far field passive effects. In addition, no liquid pool was observed as in the case of the Desert Tortoise experiments.⁵
	- *Goldfish* In a similar manner to the Desert Tortoise experiments, pressurised hydrogen fluoride was released from an elevated pipe, forming a two-phase aerosol. No rainout of the HF was observed. Concentration measurements were made from an array of sensors located on an arc at downwind distances of 300, 1000 and 3000m.
	- *Maplin Sands LPG* These experiments are similar in nature to the LNG dispersion case in the PHMSA set. LPG was spilled onto water and the continuous dispersion of the vapourising pool was monitored at various arc distances up to 650m downwind.
- Continuous releases (vertical/angled into a crosswind)
	- *Schatzmann* 4 continuous elevated vertical releases of heavy gases (Wind tunnel)
	- *Donat* 9 continuous elevated vertical, angled and horizontal releases of heavy gases (Wind tunnel)
	- Vidali 1 continuous vertical CO2 release (Wind tunnel)
	- *Engie* 3 continuous LNG vapour releases: 2 vertical, 1 horizontal
- *Thorney Island Instantaneous (see Section [4.2\)](#page-20-0)* In this experiment, approximately 2000m³ of an unpressurised mixture of Freon and Nitrogen was released at ground level. Concentrations were measured up to 600m from the release point.
- *CO2PIPETRANS (BP and Shell; see Sectio[n 4.4\)](#page-25-0)*
	- These experiments involving pressurised $CO₂$ releases were carried out at Spadeadam by GL Noble Denton (previously Advantica, currently DNV) for BP in 2006 and for Shell in 2010, with the data made available via the DNV led CO2PIPETRANS JIP. The CO₂ was released from a nozzle $(\frac{1}{4}, \frac{1}{2})$, or 1") attached to a 5.5m 2" pipe attached to a horizontal cylindrical vessel. The modelled experiments include three set of experiments, i.e. cold steady-state and time-varying releases (liquid storage), and hot supercritical time-varying releases (dense vapour storage). For the cold steady-state tests nitrogen padding gas was used to maintain the pressure and to ensure that the $CO₂$ remained as liquid in the vessel. For the time-varying tests the $CO₂$ was released through the nozzle driven only by the pressure in the vessel with the vessel pressure decaying as the release progressed. See Witlox et al. $(2014)^8$ $(2014)^8$ $(2014)^8$ for further details and references.
- *Buried Pipeline and Crater (COSHER; see Section [4.5\)](#page-35-0)*

The COSHER project was intended to understand releases from underground $CO₂$ transmission pipelines simulating loss of containment. As part of the project, two large scale experiments were completed by GL Noble Denton at Spadeadam to provide data under well- defined conditions studying the full-bore rupture of a CO² dense phase high pressure underground pipeline at large scale. Concentration data has been published from these tests, which we will refer to as COSHER 1 (Lowesmith, 2013)⁶ and COSHER 2 (Ahmad, et al., 2015). 7

• *Kit Fox (see Section [4.6\)](#page-41-0)*

In these experiments dense gas (CO₂) was released from a 1.5mx1.5m ground-level area source for continuous plumes and 20-second finite-duration releases, during both neutral and stable conditions. Experiments were carried out both for a uniform (URA; surface roughness estimated between 0.01 or 0.02 m; adopted value 0.01m) and also using an increased surface roughness (ERP; roughness estimated between 0.12 or 0.24 m closer to the source; adopted value 0.12m). Thus this set of experiments is an ideal set to investigate effects of finite-duration releases (along-wind diffusion) and effects of variable surface roughness. See Witlox et al. (2014)⁸ and the Kit Fox validation report⁹ for further details.

• *Jack Rabbit 2 (see Sectio[n 4.6\)](#page-41-0)*

In 2015 and 2016 nine large (up to ~ 10 tonnes) 2-phase chlorine releases were carried out at the US Army Dugway Proving Ground in Utah. Three were selected for validation against the UDM (1, 6 and 7). Test 1 incorporated an array of shipping containers (simulating an urban environment) and the other tests were carried out in flat terrain. Measurements of chlorine concentrations and estimates of widths were made out to a distance of 11 km downwind.

• *PHMSA Validation Set (see Section [4.7\)](#page-47-0)*

In the US, PHMSA has a process for accrediting dispersion models for use with LNG siting applications which involves comparison against a number of experiments. Many of these were already included in previous versions of this report, but we have now collated and updated them to reflect the current prescribed inputs and methods.

- *LNG Pool Dispersion*
	- *Burro* This experiment investigated the downwind dispersion that resulted from the spill of LNG onto a pool of water, 58 m in diameter and 1 m in depth. Concentrations were measured from an array of concentration sensors located on an arc at downwind distances of 57, 140, 400 and 800m.
	- *Coyote –* Like for the Burro experiments, the LNG liquid was released from an elevated height with a very low momentum. This results in almost 100% rainout onto a water basin.
	- *Maplin Sands* The experiment investigated the downwind dispersion that resulted from a spill of LNG or LPG onto the surface of the sea.
- *Continuous Release – Field Scale*
	- *Thorney Island – Continuous.* This experiment involved the continuous release of a mixture of Freon and Nitrogen. This has been modelled as a low-momentum continuous ground-level horizontal release.
- *Continuous Release – Wind Tunnel*
	- *CHRC-A, BA-Hamburg, BA-TNO*. These wind-tunnel experiments involved isothermal releases of $CO₂$ (CHRC-A) and SF $₆$ (BA-Hamburg, BA-TNO), with all modelled as vapour area sources at ground</sub> level. Only the unobstructed experiments in each series have been modelled, each at field scale rather than at wind tunnel scale.

Table 1. List of experiments for UDM validation

3 METHOD FOR UDM SIMULATIONS OF EXPERIMENTS

3.1 Definition of input data to validation runs

The input data for each validation run have been obtained from either Hanna et al (1991)¹⁰ or data sheets provided for th[e](#page-6-1) SMEDIS¹¹ project, or from the PHMSA LNG database². The Goldfish experiments are the exception to this rule, where the data were obtained from McFarlane et al¹²; see the UDM Hydrogen Fluoride verification chapter for a full discussion.

Unfortunately not all the input data required for the UDM are available from the above sources. The following general assumptions have been made when defining each validation run:

Since no flash calculations are carried out within the UDM, the UDM model requires as input the post-flash data in the case of pressurised continuous or pressurised instantaneous releases. These data are the release velocity (continuous release) or expansion energy (instantaneous release), liquid fraction and initial mean droplet size.

For cases DT1, DT2, EEC360, EEC550, EEC560, FLADIS9, FLADIS16 and FLADIS24 the release velocity and liquid fraction were supplied as part of the SMEDIS^{[11](#page-10-3)}project. The mean droplet sizes were not provided, and therefore a standalone droplet model was extracted from the Phast discharge model to calculate the mean droplet size. See the UDM thermodynamic theory manual for details.

In the remaining cases the data were obtained by running the Phast discharge model using the specified source conditions; see Section [4.1.1](#page-13-2) for a detailed comprehensive discussion.

The release velocities, $u_{cld}R$, for unpressurised releases (i.e. Prairie Grass), were obtained by dividing the release rate, m_c , by the source area, A, and the vapour density, ρ_c ^v, of the material at atmospheric temperature, T_a , and pressure, P_a :

$$
u_{cld}^R = \frac{m_c}{\left\{A \rho_c^V(T_a, P_a)\right\}}
$$
 (1)

- The default value for the solar flux has been used. $1,2$
- For those experiments in which the UDM predicts rainout the surface type is an important parameter. The choice of surface has been based on the moisture data provided, however, if this is unavailable it is assumed that the surface is wet soil.
- Two averaging times are specified by Hanna^{[10](#page-10-2)} one "short" and the other "long". The data were calculated and compared at the longest of the available averaging time. This is except for the Burro and Coyote experiments, for which calculations are carried out for both short and long averaging times (as required by PHMSA).
- The core averaging time for each validation run was set equal to the experimental averaging time. This was carried out to avoid the discontinuities that may occur when applying an averaging time correction to the centreline concentration and cloud width after the transition to passive dispersion.
- UDM simulations for each validation experiment were carried out including the effects of both heat and (in case of dispersion above water) water transfer.

Further details of input data assumptions related to the individual experiments are presented in Chapter [4,](#page-13-0) while [Appendix A](#page-57-1) lists the precise values of the input data used for the UDM simulation of each validation case is presented in [Appendix A.](#page-57-1)

 1 Note that a relation exists between solar flux and the time of year and cloud cover. Since this relation is not implemented in the UDM model, it is chosen to adopt the default value (500 W/m²), which may well be inaccurate

 2 The solar flux is used exclusively within the pool model. It is shown by a sensitivity analysis that solar flux has little impact to the pool model predictions for spill on land.

3.2 Calculation of output data to validation runs

This report provides a graphical representation of the UDM predictions for each individual experiment. These figures also include comparison with the available experimental data. These were obtained from either Hanna et al^{[10](#page-10-2)} (including Goldfish) or SMEDIS data sheets^{[11](#page-10-3)}. The majority of experiments measured concentrations at one single height. However, a selection of the experiments, for example FLADIS and Desert Tortoise, measured concentrations at a number of different heights.

For each experiment the following figures are produced:

- a) Centreline concentration, $c(x, 0, z_{cld})$, and concentration at a specified height H, $C(x, 0, H)$, as a function of downwind distance, x(m).
- b) Centre-line height z_{cld} (m) as a function of downwind distance $x(m)$.
- c) Cloud width and cloud depth, $H_{\text{eff}}(1+h_d)$, (m) as a function of downwind distance. See [Appendix B](#page-81-0) for the full definition of cloud width. The definition for the cloud depth is laid out in the theory manual
- d) Vapour and liquid temperature (K) as a function of downwind distance

For two-phase releases that form an evaporating pool the figures show the resulting dispersion for each pool segment.

3.3 Statistical measures of performance

Each experimental set (or series) was statistically evaluated to determine the accuracy and precision of the UDM predictions with the observed data. Formulas, as reported by Hanna et al.^{[10](#page-10-2)}, were used to calculate the geometric mean bias, MG, and geometric variance, VG, for an experimental dataset.

Single experiment

A single experiment with N data points is considered. Let *x⁰* = [*x01, x02,* …. *x0N]* be the array of observed data, and *x^P* be the array of predicted data = [*xP1, xP2,* …. *XPN]*. The geometric mean bias (MG) and variance (VG) are now defined as follows³

$$
MG = \exp\left(\overline{\ln x_o} - \overline{\ln x_p}\right) = \exp\left(\overline{\ln \frac{x_0}{x_p}}\right) = \exp\left[\frac{1}{N} \sum_{i=1}^{N} \ln\left(\frac{x_{0i}}{x_{p_i}}\right)\right]
$$
 (2)

$$
VG = \exp\left[\left(\ln x_0 - \ln x_P\right)^2\right] = \exp\left[\ln\left(\frac{x_0}{x_P}\right)^2\right] = \exp\left[\frac{1}{N}\sum_{i=1}^N \ln\left(\frac{x_{0i}}{x_{pi}}\right)^2\right]
$$
 (3)

where *Σ* refers to summation of over the N data points, and χ indicates a mean variable,

$$
\overline{\chi} = \frac{1}{N} \sum_{i=1}^{N} \chi_i
$$
 (4)

Ideally, MG and VG would both equal 1.0. Geometric mean bias (MG) values of 0.5 and 2.0 can be thought of as a factor of 2 in over-predicting and under-predicting the mean, respectively"¹³. Likewise, a geometric variance (VG) of about 1.6 indicates scatter from observed data to predicted data by a factor of 2.

Dataset with multiple experiments

Secondly a dataset with M multiple experiments considered. For experiment j ($j = 1, \ldots, M$), the arrays of observed and predicted data are given by

 3 In the MG formula for the concentration, both observed and predicted concentrations are set equal to a threshold concentration if their values are below this threshold (default = 0.001 mole %).

$$
x_{0j} = [x_{01j}, x_{02j},..., x_{0N_jj}], \quad x_{Pj} = [x_{P1j}, x_{P2j},..., x_{PN_jj}]
$$
 (5)

Where N_i is the number of data points from experiment j.

The values MG_{tot}, VG_{tot} for the total dataset can be derived from the values MG_i, VG_i associated with the individual experiments as follows:

$$
MG_{tot} = \exp\left[\frac{1}{N_{tot}} \sum_{j=1}^{M} \sum_{i=1}^{N_j} \ln\left(\frac{x_{0ij}}{x_{Pij}}\right)\right] = \prod_{j=1}^{M} \left\{ \exp\left[\frac{1}{N_j} \sum_{i=1}^{N_j} \ln\left(\frac{x_{0ij}}{x_{Pij}}\right)\right] \right\}^{\frac{N_j}{N_{tot}}} = \prod_{j=1}^{M} \left\{ MG_j\right\}^{\frac{N_j}{N_{tot}}}_{\frac{N_{tot}}{N_{tot}}} \tag{6}
$$

$$
VG_{tot} = \exp\left[\frac{1}{N_{tot}} \sum_{j=1}^{M} \sum_{i=1}^{N_j} \ln\left(\frac{x_{0ij}}{x_{Pij}}\right)^2\right] = \prod_{j=1}^{M} \left\{ \exp\left[\frac{1}{N_j} \sum_{i=1}^{N_j} \ln\left(\frac{x_{0ij}}{x_{Pij}}\right)^2\right] \right\}^{\frac{N_j}{N_{tot}}} = \prod_{j=1}^{M} \left\{ VG_j\right\}^{\frac{N_j}{N_{tot}}} \tag{7}
$$

where *Π* refers to a product for all datasets, and the total number of data points N_{tot} is given by

$$
N_{tot} = \sum_{j=1}^{M} N_j
$$
 (8)

Thus it follows that:

$$
MG_{tot} = \left\{ \prod_{j=1}^{M} \left(MG_j \right)^{N_j} \right\}^{J'_{N_{tot}}}, \hspace{0.5em} VG_{tot} = \left\{ \prod_{j=1}^{M} \left(VG_j \right)^{N_j} \right\}^{J'_{N_{tot}}} \hspace{1cm} (9)
$$

In case all experiments have the same number of data points, i.e. $N_1=N_2=...=N_M$, the above formulas further reduce to:

$$
MG_{tot} = \left\{ \prod_{j=1}^{M} \left(MG_{j} \right) \right\}^{\frac{1}{N}} , \quad VG_{tot} = \left\{ \prod_{j=1}^{M} \left(VG_{j} \right) \right\}^{\frac{1}{N}} \tag{10}
$$

The above formul[a \(10](#page-12-0)) has been used for the Kit Fox experiments (where 4 data points apply for each experiment), while the other more general formula [\(9](#page-12-1)) has been used for the other experiments. However for some cases one may consider to use nevertheless equation [\(10](#page-12-0)), e.g. to avoid that an experiment j with many experimental data points influences too much the total values MG_{tot} and VG_{tot}. This should be decided on the basis of the given dataset!

4 RESULTS AND DISCUSSION

4.1 Continuous releases (excluding CO2)

4.1.1 Discharge data for two-phase jets

This section⁴ details the results of discharge calculations associated with two-phase jets, i.e. the FLADIS ammonia, Desert Tortoise ammonia, EEC propane and Goldfish HF experiments. Input data for these calculations as well as additional input required for the dispersion calculations were obtained from SMEDIS for FLADIS, Desert Tortoise and EEC. For the Goldfish HF experiments, input data were obtained from Chapter 9 of the HGSYSTEM 1.0 Technical Reference Manual¹⁴. Note that these input data for Goldfish differ from those used in the MDA by Hanna et al.^{[10](#page-10-2)}, while the SMEDIS Desert Tortoise data are in line with the values in the MDA. The data provided for the FLADIS experiments are in line with those presented by Nielsen and Ott¹⁵.

The discharge calculations have been carried out using the leak scenario of the Phast discharge model DISC (version 7.1):

- The DISC model has two methods for modelling the expansion from stagnation conditions to orifice conditions, i.e.
	- \circ the metastable liquid assumption: non-equilibrium at the orifice, liquid remains liquid at the orifice, orifice pressure = ambient pressure
	- \circ flashing liquid assumption: equilibrium at the orifice, flashing may occur upstream of the orifice
- The DISC model has also the following three options for performing the expansion from the choke point in the orifice to the atmospheric pressure, namely:
	- o Isentropic
	- o Conservation of momentum
	- o (default option) One of the two options above, with the option selected which results in minimum thermodynamic change between orifice conditions and final conditions. For all current sets of experiments, it was found that this default option corresponded with the isentropic option.

[Table 2](#page-15-0) summarises the DISC input data and results for the case of the default assumption of metastable liquid assumption in conjunction with conservation of momentum.

Flow rate predictions

[Table 3](#page-16-0) first compares observed flow rates (reported by SMEDIS for the FLADIS, EEC experiments and by Hanna for the DT, GF experiments) against DISC predictions for both cases of 'metastable liquid' and 'flashing':

- It is concluded that the Goldfish predictions are virtually identical for both cases with very close agreement with the data.
- Predictions for EEC and DT presuming 'flashing' are seen to provide considerably improved predictions compared to the 'metastable liquid' assumption. On the other hand, FLADIS results are best presuming 'metastable liquid', with significant under-prediction presuming 'flashing'. Overall the 'metastable liquid' is seen to provide conservative results, with an over-prediction of the observed flow rates.

Note there is an inherent inaccuracy in the measured flow rates with e.g. an accuracy of 18% quoted by Nielsen and Ott^{[15](#page-13-3)} for the case of the FLADIS experiments.

The results given i[n Table 3](#page-16-0) are obtained by quick DISC simulations, and more accurate estimate of the input as well more accurate method of modelling may be able to be obtained by means of a more thorough analysis of the experimental data sets. However this was not part of scope of the current work.

Predictions of post-expansion data: liquid fraction, velocity and Sauter Mean Diameter (SMD)

[Table 3](#page-16-0) secondly compares predictions of post-expansion data using the range of model assumptions as described above, and compares these predictions against values of liquid fraction and velocity provided as part of the SMEDIS project:

- Post-flash liquid fractions provided by SMEDIS are in close agreement with the DISC predictions
- **Velocity**

 4 UPDATE. Part of the description of this section may be moved to the ATEX validation report^{[16](#page-14-0)}, with a summary retained only in the current section only.

- o DISC predictions of final post-expansion velocity presuming metastable liquid assumption are lower than presuming 'flashing' upstream of the orifice. DISC predictions of velocities presuming conservation of entropy result in significant larger velocities than presuming conservation of momentum.
- o For the case of the FLADIS experiments, SMEDIS values for velocity are closest to the DISC predictions presuming metastable liquid and conservation of momentum. On the other hand, for the EEC and Desert Tortoise experiments, the SMEDIS values are closest to the DISC predictions presuming flashing and conservation of momentum. Using the isentropic approach, DISC predicts post flash velocities which are much higher than those provided as part of the SMEDIS project.

Selection of model assumptions

As indicated above regarding accuracy of flow-rate predictions and agreement of final post-expansion velocity with SMEDIS data, it could be considered to apply the 'flashing' assumption for the Desert Tortoise and EEC experiments. However it was found (see ATEX validation report¹⁶) that the metastable liquid assumption generates overall more accurate predictions (improved MG,VG values) using the metastable liquid assumption for all sets of experiments (FLADIS, Desert Tortoise and EEC).

With these observations in mind, it was concluded that any non-SMEDIS validation sets, which required post flash data, would obtain them using the Phast discharge model, adopting the conservation of momentum approach in conjunction with the metastable liquid assumption⁵. Thus this approach has been used to obtain values for all post-expansion data (liquid fraction, velocity, SMD).

[Table 3](#page-16-0) also gives droplet SMD values. The modified CCPS correlation (introduced as the default in Phast 6.7) was used. This should for these cases use the CCPS flashing correlation, but for the conservation of momentum method in conjunction with metastable liquid assumption in fact it uses the mechanical correlation⁶ and thus SMD values may be less accurate. However in case rainout would not occur, the precise value of the SMD is not expected to significantly affect the dispersion calculations.

⁵ UPDATE. At a later stage, it may be considered to no longer use the SMEDIS input data for the SMEDIS validation sets, and to use for these the same approach as for the non-SMEDIS validation datasets.

 6 Due to calculated partial expansion energy being < 0 (warning ATEX 1010)

Table 2. DISC input spreadsheet for large-scale flashing experiments (FLADIS, EEC, DT, GF) – metastable liquid assumption

Table 3. Large-scale flashing experiments: flow rate predictions, SMEDIS versus Phast 7.1 post-expansion predictions

 \overline{a}

^{vii} Previously SMD was presumed 40 micrometer, but now it has been calculated as 45 micro meter. Given the small difference, the original value of 40 micro meter has been obtained.

4.1.2 Dispersion

The results of the statistical comparison of the UDM predictions with the centre-line concentration measurements for the continuous experiments are presented in [Table 4.](#page-18-0) The following observations may be made:

- For the neutrally buoyant, Prairie Grass experiments, the UDM performance is satisfactory. The UDM significantly over-predicts the measured centre-line concentration in the case of run 7.
- The UDM predictions of the measured centre-line concentrations in the Desert Tortoise experiments are very good.
- The performance of the UDM against the EEC experiments is reasonable.
- The UDM performance is good for the centre line concentration predictions in the FLADIS experiments, with a slight over-prediction observed in general.
- The UDM under-predicts the centre-line concentrations for the Goldfish experiments. A closer investigation indicates that agreement between predicted and experimental results is good prior to the transition to passive dispersion. Downwind of the transition the under-prediction increases due to the larger passive spread rate^{viii}. Furthermore, the under-prediction of the centre-line concentrations and over-prediction of the cloud width may be related to the absence of a gravity collapse criterion in the UDM.
- The UDM under-predicts the centre-line concentrations for the Maplin Sands LPG experiments. It is noted that while the Phast defaults are used here, the results are sensitive to the particular choice of parametersix

The statistical comparison of the UDM cloud width predictions with the experimental data are also presented in [Table 4.](#page-18-0) The following conclusions may be drawn:

- The performance of the UDM against the neutrally buoyant Prairie Grass experiments is good.
- The performance of the UDM against the aerosol releases of Desert Tortoise, EEC and FLADIS, in which both heavy and jet entrainment dominates, is reasonable.

^{viii} All the validation cases were rerun with the Richardson Number transition criterion temporarily set to a lower value of 2.5. The Goldfish series of experiments were the only cases that were seriously affected, giving better comparison against experimental data. However, it was noted that the distance to passive transition increased dramatically, possibly leading to a large under-prediction of averaging time effects. With this observation in mind the Richardson number transition criterion was left at the current value of 15.

ix In particular the choice of number of pool observers. The default of 10 is used here but increasing this number improves agreement with observed concentrations.

Table 4: MG and VG values for centre-line concentrations and widths (continuous)

^x No summary width given – mixture of Hann and SMEDIS methods

4.2 Continuous releases (angled & vertical)

In this section we are specifically concerned with continuous releases (typically vertical or angled) into a crosswind. There are a number of experimental studies to validate against here, although given the nature of the geometry these are usually wind tunnel studies of heavy gas releases, with the Engie experiments being the only field-scale cases considered. We have introduced this validation set from Phast 8.6 to coincide with the "Morton extended" model being introduced as default. This model addresses observations that for previous releases of Phast there has been a systematic tendency to underestimate near-field dispersion distances for vertical releases.

In most of these experiments, arrays of sensor locations are arranged vertically at fixed downwind locations on the centre line, and the concentration distribution along the vertical array reported. An example is shown in [Figure 1.](#page-20-1) At each downwind observation location we can use the maximum concentration and the height at which this concentration was observed for comparison with calculations^{xi}.

The validation set comprises 17 individual experiments:

- Schatzmann et al¹⁷. : 4 wind-tunnel experiments, all vertical.
- Donat¹⁸: 9 wind-tunnel experiments, 6 vertical, 1 angled, 2 horizontal.
- Vidali et al.¹⁹: 1 vertical wind-tunnel experiment.
- Quillatre²⁰ (Engie): 3 field experiments, 2 vertical, 1 horizontal

All wind-tunnel cases have been simulated at field-scale rather than wind-tunnel scale, and the appropriate input data are presented i[n Table 5](#page-21-0)

Figure 1: Concentration reporting in crosswind experiments (from Schatzmann et al)

^{xi} This way we can separate out trajectory and entrainment comparisons. If we were to use concentrations at specific (sensor) points, a poor estimate of height would inevitably lead to a low concentration prediction.

Table 5. Phast input data for the crosswind calculations (Schatzmann, Donat, Vidali and Engie)

Calculated MG and VG for the predicted centreline concentration at the downwind observation points are presented in [Table 6](#page-22-0) and plotted in [Figure 2](#page-23-0) where the different experiments are plotted as separate series. These use the new 'Morton extended' model.

We see particularly from [Figure 2](#page-23-0) that the data points are scattered evenly around MG=1, demonstrating that the new default model does not present any observable bias to overpredict or underpredict these experiments. Most cases sit in a narrow band around MG=1 and well within the 'factor of 2' range.

The extent of the of improvement in comparison with Phast 8.4 is shown i[n Figure 3,](#page-23-1) where the Phast 8.4 points can be seen to underpredict across all experiments. The extension of this model to include high velocity vertical releases is expected in future work.

Table 6. MG and VG values for the maximum plume centreline concentration

Figure 2: MG and VG plots for the plume centreline concentration

Figure 3: MG and VG plots for the plume centreline concentration (8.6 vs 8.4)

4.3 Instantaneous dispersion

Table 4 includes the results of the statistical comparison of the UDM predictions of the centreline concentration with the measured experimental data. As can be seen the performance is somewhat variable with an overall trend towards over-predicting the experimental data. Predictions for runs 7, 9 and 12, which are at relatively low wind speeds, are less accurate.

Table 7. MG and VG values for centre-line concentrations (instantaneous),

4.4 Pressurised CO2 releases (BP and Shell experiments)

[Figure 4](#page-25-3) depicts the Phast modelling of discharge and dispersion for an elevated two-phase pressurised release. The discharge modelling includes the expansion from orifice (pipe exit) conditions to atmospheric pressure during which liquid to solid/vapour expansion occurs. In case of initial supercritical temperature (above 31° C), vapour to vapour, or vapour to two-phase solid-vapour expansion occurs. The applied Phast discharge models are DISC (steady-state releases) and TVDI (time-varying releases) and they predict the post-expansion conditions subsequently used as the source term (starting condition) for the UDM dispersion model. The discharge and dispersion modelling allows for the presence of solid $CO₂$ downstream of the orifice/pipe exit.

Figure 4. Discharge modelling (DISC/TVDI) and dispersion modelling (UDM)

4.4.1 Phast discharge model predictions

For the Shell experiments, the flow rate and density were measured accurately using a coriolis flow meter. In addition for both the Shell and BP experiments, the vessel weight was measured using load cells. Thus for the BP supercritical vapour releases, the flow rate was derived from the measured vessel weight using load cells. For the BP cold steady-state liquid releases, the flow rate was estimated by Advantica (Evans and Graham, 2007)²¹ from the load cells by assuming that the total flow rate (kg/s; derived from vessel mass as measured by the load cells) equals dM/dt = ρCO2VCO2 – ρN2VN2. Here ρCO2 is the CO2 density (kg/m3), VCO2 the CO2 volume rate (m3/s), ρN2 the nitrogen density (kg/m3), and VN2 the nitrogen volume flow rate (m3/s). Pressure and temperature were measured at a range of locations upstream of the vessel, inside the vessel, and downstream of the vessel along the pipe and the release valve.

The Phast discharge models either assume the release to be directly from an orifice from a vessel ('Leak' scenario), or from a short pipe attached to a vessel (with orifice diameter = pipe diameter, i.e. full-bore rupture). Except for the 1" orifice tests (BP test 5 and Shell tests 2,5), the observed pressure at the discharge end was seen to be very close to the observed pressure at the vessel inlet and vessel outlet. Thus the Phast 'Leak' scenario was applied, while neglecting the pressure loss from the stagnation conditions to the nozzle conditions. Also the 1" orifice tests can be modelled using the 'Leak' scenario, provided that measured nozzle pressure/temperature are specified as model input instead of storage pressure/temperature (at vessel outlet).

The Phast discharge model DISC was used to simulate the steady-state liquid releases, while the Phast discharge model TVDI was used to model the time-varying releases. Default Phast parameters were applied with two exceptions. First the metastable assumption (non-equilibrium with liquid 'frozen') was not applied, but flashing was allowed at the orifice (equilibrium at the orifice) to account for the pipework upstream of the orifice. Secondly, conservation of momentum was applied for the expansion from orifice to post-expansion conditions, since this assumption was previously found to provide source terms giving the most accurate concentration predictions by the subsequent UDM dispersion model [e.g. against the SMEDIS experiments; [4.1.1](#page-13-2) for details].

4.4.1.1 Time-varying releases

[Table 8](#page-26-1) shows that the measured initial CO2 density derived from the coriolis flow meter for the time-varying Shell tests is very close to values predicted by the Span-Wagner (SW) equation of state in line with recommendations of a report by EON (2011). Also accurate predictions are obtained of the liquid density in Phast using the (non-default)

Peng-Robinson (PR) equation of state (EOS). The default method in Phast presumes the liquid density equal to the saturated liquid density at the given temperature, i.e. independent of the pressure. This was shown to result in accurate predictions of the liquid density after depressurisation to saturated conditions, but to lead to a significant under-prediction of the initial liquid density (i.e. total initial vessel mass).

[Table 8](#page-26-1) also demonstrates that improved predictions are obtained of the initial vapour density for the hot tests 14 and 16 using the PR equation of state.

Table 8. Predicted versus observed initial CO² density for time-varying Shell tests

[Figure 5](#page-27-1) includes TVDI-predicted (default Phast density) and observed values for flow rate (kg/s) versus time (s) for the time-varying releases. The thick solid lines represent the experimental data. The other lines represent TVDI predictions, while allowing flashing at the orifice.

For the liquid releases, [Figure 5a](#page-27-0) includes TVDI predictions using both the default EOS and (using a new more robust development version of TVDI) the PR EOS. The default EOS predicts both the initial flow rate and the flow rate after depressurisation to saturated conditions quite accurately. However less accurate results are obtained during the regime of depressurisation to saturated, with a too rapid decrease of flow rate caused by the usage of the too low saturated liquid CO2 density. The PR EOS using a more accurate CO2 density provides more accurate predictions of the flow rate for all regimes.

For the hot vapour releases,

[Figure 5b](#page-27-1) includes predictions of the current TVDI model (version 6.7) using both the default EOS and the PR EOS. For the BP tests, the observed values for the flow rates are averaged over a period over 8 seconds to reduce oscillations caused by inaccuracies of the load-cell measurements. This was not necessary for the coriolis flow meter measurements. The following can be concluded from [Figure 5b](#page-27-1):

- For the very hot BP tests 8, 8R (storage temperature about 150oC), the vapour remains vapour within the vessel upon depressurisation (condensation not relevant), and it is seen that very close agreement is obtained between TVDI predictions and observed data using both the default and PR EOS, since they both provide very accurate predictions of CO2 vapour density.
- For the BP test 9 and the Shell test 14 (temperature about 70oC), PR EOS is seen to produce most accurate results. Furthermore the default-EOS TVDI runs are seen to terminate prematurely, which was due to convergence problems apparently caused by the release temperature being lower and closer to the critical temperature. An under-prediction of the flow rate is seen at larger times.
- For Shell test 16 the above effects are seen to be even more pronounced, since the initial storage temperature is only a few degrees above the critical temperature. At larger times the vessel fluid may become liquid, but the transition from vapour to liquid is not modelled by TVDI resulting in under-prediction.

Figure 5. TVDI validation of flow rate for time-varying CO2 releases (BP&Shell tests)

4.4.1.2 Initial rate for steady-state and time-varying releases

BP tests

[Table](#page-65-3) **29** summarises the overall results of the discharge rates for all BP tests. For the steady-state tests only the DISC initial release rate is given, while for the time-varying releases also the TVDI-predicted averaged release rate over the first 20 seconds is indicated. It is noted that the difference between the averaged and initial rate is relatively small. From the table it is seen that the time-varying Phast predictions align well with the observed discharge rate for the hot tests 8, 8R and 9. The predicted flow rate for the cold releases, with the exception of test 5 (1" release), is also very close to that of the experiments.

Table 9. Predicted versus observed flow rates; UDM source-term data (BP CO² tests)

For test 5 (1'' release) the flow rate is over-predicted with 23% (50.74 kg/s predicted versus 41.17 kg/s experimental) using the 'Leak' scenario, while using the pipe ('Line Rupture') scenario it is under-predicted with 34.5% (26.95 kg/s predicted versus 41.17 kg/s). The over-prediction for the orifice scenario is believed to be caused by the fact that pressure loss is ignored along the pipework (hose/spool/nozzle). Test 5 has the largest orifice diameter (1") and therefore will be most susceptible to upstream pressure loss and reduced flow rate. Indeed if a more accurate pressure would be applied of 128.6 barg (corresponding to averaged observed pressure close to the orifice) a release rate of 45.34 kg/s is predicted using the 'Leak' scenario corresponding to a much smaller over-prediction of 10.1%.

As indicated above the flow rate changes little for the time-varying tests 8, 8R, 9 within the first 20 seconds, and it is believed that within 20 seconds the maximum concentrations will be achieved within the first 80 meter (given relatively large initial jet momentum and relatively large values of wind speed). Therefore in the next section the dispersion calculations are modelled as steady-state using the averaged flow rate over the first 20 seconds for tests 8, 8R and 9, while for the other tests the values observed over the duration is adopted; see Evans and Graham^{[21](#page-25-4)} on further details of the evaluation of the observed flow rate. All other UDM input data (temperature, solid fraction, velocity) are chosen as predicted above by the discharge model DISC.

Shell test[s](#page-29-3)

[Table](#page-29-3) **10** summarises the overall DISC predictions of the initial discharge rates for all Shell tests. In this table a range of model assumptions is applied:

- Time-varying releases are calculated either based on measured initial storage (vessel outlet) pressure/temperature or measured initial nozzle pressure/temperature; as expected, particularly for the largest 1" orifice size (test 2), usage of nozzle data significantly improves the predictions given the significant pressure decay between storage and nozzle conditions; for the smallest ¼" orifice size identical results are obtained because of negligible pressure decay.
- Phast liquid density either based on default (saturated density) or more accurate Peng Robinson density, with more accurate results obtained using the Peng-Robinson equation of state
- Flashing (non-default Phast) or non-flashing (default Phast; metastable liquid assumption). Using Peng-Robinson density, this is seen to affect results very little. Using the saturated density, the default nonflashing option provides conservative results while the non-default flashing assumption produces significantly more accurate results.

Table 10. Predicted versus observed flow rates – vary Phast assumptions (Shell tests)

Table 11. Predicted versus observed flow rates and UDM source-term data (Shell tests)

[Tabl](#page-29-4)**e 11** includes results and UDM source terms based on nozzle data, the Peng-Robinson Equation of state and the flashing assumption. Note that unlike the BP experiments, the UDM dispersion data are chosen to depend on the initial rate rather than on the averaged rate during the first 20 seconds. This choice was made, since as discussed later the concentration sensors only measured accurately the initial concentration, and not the concentration at subsequent times.

4.4.2 UDM dispersion predictions

The CO2 concentration was largely measured via O2 cells for both BP and Shell experiments; see [Figure 6](#page-30-1) [taken from Allason and Armstrong $(2011)^{22}$] for the location of the O2 concentration sensors. Thus a total of 43 sensors was applied at downstream distances of 5m (sensor OC01), 10m (OC02), 15m (OC03), 20m (OC04-OC08), 40m (OC9-OC21), 60m (OC22-OC28) and 80m (OC29-OC43), with sensors position at a range of different heights (0.3, 1 or 3 m) and cross-stream distances (between -20 and +20 degrees from the release direction) with two additional Servomex CO2 analysers.

Figure 6. Field detector array for concentration measurements (Shell CO2 tests) Figure corresponds to Shell tests, but concentration sensor location is also applicable to BP tests.

Phast assumes that the release direction is the same as the wind direction, while for some of the experiments (see [Table 29](#page-65-1) and [Table 30\)](#page-65-2) there is a significant deviation from the wind direction. This may lead to less accuracy of the predictions in the far-field but will not significantly affect the prediction for the momentum-driven dispersion in the near-field.

BP tests

[Figure 7](#page-31-0) plots for test 11 the maximum values over time of the measured concentration along with the Phast predicted concentrations as a function of downstream distance. The measured data include the maximum concentration of the raw data over all times, 11-second, 20-second and 59-second averaged concentrations. For the measured data at a given downstream distance the maximum value of all sensors at that distance is taken, Sensor 14 (located at 40m downstream, 3 meter height) has been excluded since it appeared to give erroneous too high readings (higher than sensors at 1 meter height and sensors further upstream). Furthermore no further analysis has been carried out (e.g. via spline fitting of the measured values to obtain a better fit of the crosswind concentration profile and a better estimate of the maximum concentration) to further refine this maximum value. The Phast predictions were found not to be affected by time-averaging effects due to plume meander (transition to passive dispersion occurring downwind of 80m).

In the near field (< 20 m) the 59-seconds averaged concentration predicted by Phast is close to the measured concentrations. This is also in line with UDM validation against previous experiments, where very close agreement was obtained in the near-field, jet-momentum dominated regime. Further downstream (at 20 meter and 40 meter) it is seen that the spread in the measured concentrations becomes larger with a larger effect of averaging. This is because of (a) larger relative inaccuracy of the sensors, and (b) the CO2 plume centre-line more likely to be further away from the sensor (also because of plume meander). Thus for this case, as is clearly illustrated by Figure 9 , the maximum value would lead to too large (rather random) value of the maximum concentration (it would increase with the release duration), while on the other hand the 59-second averaged concentration may lead to too small values.

Figure 7. BP Test 11 – UDM validation for maximum contraction versus distancexii

Figure 8. BP Test 9 – UDM validation for maximum concentration versus distance

^{xii} Very close agreement confirmed between 7.1 and UDM AWD results; therefore no update of [Figure 7,](#page-31-0) [Figure 8,](#page-31-1) [Figure 9,](#page-32-0) [Figure 10](#page-33-0) an[d Figure](#page-33-1) 11.

[Figure](#page-31-2) **8** includes results of UDM validation for maximum concentration versus downstream distance for the timevarying test 9 (vapour release). It is again seen that good agreement with the processed averaged experimental data is obtained. For this test, sensors 17 and 14 were considered to give possible incorrect readings for similar reasons to sensor 14 in test 11.

Shell tests

For the Shell tests, a limited number of 3rd party commercial CO2 detectors including instruments from Draeger as well as two Servomax gas analysers were used in addition to the O2 sensors in order to verify the accuracy of the O2 sensors. From the results of this it was deduced that the O2 sensors did reasonably predict the initial (maximum) value of the concentration, but did subsequently show an erroneous decay with time which could have been caused by significant cooling of the sensors. This erroneous behaviour of the O2 sensors was confirmed by the experimentalists.

[Figure 9,](#page-32-0) [Figure 10](#page-33-0) and [Figure](#page-33-1) 11 plot for tests 11 (steady-state cold release), 16 (transient hot release) and 1 (transient liquid release) the maximum values over time of the measured concentration along with the Phast predicted concentrations as a function of downstream distance. The measured data include maximum values and (for steady-state test 11 only) averaged values (over release duration) for the O2 sensors, Servomax sensors, and (if present) Draeger sensors.

Overall it is seen that the maximum O2 values agree well with the UDM predictions, where negligible difference was observed between UDM predictions at 1 meter release height and centre-line (C/L) height. Because of erroneous decay with time, the averaged O2 values result in too low observed values for Test 11. The maximum concentration derived from the Draeger sensors is reasonably aligned with that derived from O2 sensors, but it is particularly less accurate in the far-field because of an insufficient number of sensors (and thus the Draeger sensors may miss the centre-line of the plume).

Figure 9. Shell Test 11 – UDM validation for maximum contraction versus distance

Figure 10. Shell Test 16 – UDM validation for maximum concentration versus distance

Figure 11. Shell Test 1 – UDM validation for maximum concentration versus distance

4.4.3 Comparison statistics between predicted and observed concentrations

[Table 12](#page-34-2) and [Figure 12](#page-35-2) include the predictions of MG and VG for the BP and Shell experiments. It is noted that all MG values are well within the range of [0.5, 2], and all variances less than 1.6 which is normally considered to be excellent agreement with the experimental data. In [Table 12](#page-34-1) and [Figure 12](#page-35-2) the observed maximum concentration at a downstream distance is taken as the maximum value of all sensors at that downstream distance.

Table 12. UDM values of MG and VG for BP and Shell CO² experiments

Figure 12. UDM values of MG and VG for BP and Shell CO2 experiments

For the BP experiments, the maximum value over all times of the 11-second averaged concentrations has been applied and sensors of apparent false readings have been ignored. Therefore conservative estimates are obtained of the averaged observed concentrations for the steady-state cold releases (1, 2, 3, 5, 6, 11), which may (partly) explain the under-prediction of the concentrations for the experiments 2, 3, 5, 6. For tests 1, 3, 6 there was a significant difference between the wind direction (averaged over the entire release duration) and the release direction. However the above results show that the plume centre-line did not significantly miss the sensors. Further downstream this may have been caused because we adopt 11-second averaged concentrations (maximum overall all times) rather than concentrations averaged over the entire release duration. Furthermore it must be noted that for tests 3 and 6 a 2" 1.44 m extension tube was attached downstream to the $\frac{1}{2}$ " (test 3) and $\frac{1}{4}$ " (test 6) nozzle, which is not expected to affect the discharge flow rate but is likely to have affected the dispersion. This may explain the largest under-prediction of the concentrations (largest MG values) for tests 3 and test 6.

For the Shell experiments, maximum concentrations for the O2 sensors were used, and none of the O2 sensors was ignored even though they may provide a less accurate reading. This may have caused the overall underprediction for the Shell experiments. Furthermore for the steady-state releases a higher accuracy is obtained than for the BP experiments, because of (a) input of more accurate measured flow rate and (b) use of conservative 11 second average estimate (maximum over all times during release duration) for the BP experiments.

4.5 Buried pipeline / Crater Releases (COSHER)

4.5.1 Facility and measurement grid

Both of the COSHER experiments used the same facility at the GL test site at Spadeadam. It comprised a 117.1 m long, 1321 mm (52") diameter steel pipeline connected to a 226.6 m long pipeline loop formed from 200 mm (8") diameter steel pipe. A 4 m rupture spool was located at the halfway point of the loop. The arrangement is shown in [Figure 13](#page-36-0) (Ahmad, et al., 2015).

Figure 13: The experimental facility

Details of the test rig are given in Tabl[e Table 13.](#page-36-0)

Summary of dimensional and constructional information of the rig.

Table 13. The COSHER test rig

The sensor locations are given for Test 1 by Lowesmith, though are likely the same for Test 2. However for each test wind direction is different, and locations must be corrected. The locations relative to a fixed grid north are shown in [Figure 14.](#page-37-0)

Figure 14. Instrumentation locations

Table 14. The COSHER test conditions

Ahmad and Lowesmith observe that the release was (pseudo-) steady state between 50-180s (Test 2), and 50- 250s (Test 1). Using the long-pipeline model as described above (i.e. in the absence of a 52" storage reservoir) produces a strongly time-varying release, and so we have represented it used a single segment averaged over a time (10 s for Test 2, 20s for Test 1) such that the rate closely matches the experimentally observed one. The resulting source term is shown i[n Table 15.](#page-38-0)

xiii Using location L02 as suggested in text

Table 15. Baseline Phast source term from matching release rates

4.5.2 Crater modelling

Buried pipelines invoke the crater model. This predicts the size and shape of crater formed immediately after the rupture, as well as a reduction in velocity and a mass of air entrained by mixing within the crater. These modifications are given at the bottom of [Table 15.](#page-38-0) It is not clear what crater size correlations predict – averaged or maximum dimensions. Here the observed maximum dimensions are given, as these are clearer to interpret from the published information (essentially plan views).

Table 16. Maximum observed and predicted crater dimensions

Also given are the predictions of the correlations for natural gas pipelines by Ramirez-Camacho et al. (2019) derived from multivariate regression of historical accident data.

4.5.3 Concentration measurements

The UDM is run using the post-crater source term. We left all parameters at default values. Validation data came from Figures 11 and 12 in the Ahmad paper and Figures 32-35 in Lowesmith. We captured at the sampler locations the maximum concentration for each time series and compared it with Phast predicted maximum concentrations. In addition we used a subset of these as the arcwise maximum concentrations – i.e. for a given arc (50m, 100m etc) the maximum experimental concentration.

The sampler locations from the paper were adjusted to account for a wind direction offset of 9° and 15 $^{\circ}$ from the sampling grid. The local sensor heights of 1m was used universally, although Ahmad suggests some sensor locations may have been at a height of 1.8m. .

For the reduced set of arcwise maximum comparison, the Y co-ordinate of all points for the simulation was set to zero

xiv Not measured directly – estimated from inventories

4.5.4 Dispersion Results

The maximum concentrations (observed and predicted; arcwise and pointwise) for the two COSHER tests are shown in [Figure 15](#page-39-0) and [Figure 16.](#page-40-0)

Figure 15. Maximum arcwise concentration for COSHER experiments

[Figure 16. Maximum pointwise concentration for COSHER experiments](#page-40-1)

[Table](#page-40-1) **17** gives the summary MG and VG values for arcwise and pointwise concentrations

Table 17. Arwise and pointwise MG/VG values for COSHER CO² simulations

The results indicate good agreement between Phast and the experimental concentrations. Cosher 1 does show some under-prediction at low pointwise concentrations, but this is mainly limited to concentrations below the 1% level and therefore of less interest for CO₂ toxicity.

Results are much improved over previous (v8.71 and earlier) Phast versions, which greatly under-predicted ground level concentrations – especially upwind and crosswind of the release point.

Both cases are using the new defined-area source term model, and the gas blanket dispersion model. These are the default options in v8.9 for CO₂. Those interested are referred to the Crater Model and UDM Theory technical documents for further details.

4.6 Finite-duration dispersion

4.6.1 Kit Fox experiments

UDM input data have been obtained from the MDA database given by Hanna and Chang (1999)²³; see Appendi[x A.4.](#page-70-0) The ground-level area source is modelled as a circular source of vapour-phase CO2 with diameter 1.69 m with corresponding source area A equal to that of the actual 1.5m x 1.5m square source; se[e Figure 17.](#page-41-0)

Figure 17. Plot plan of the Kit Fox site

In this section results are reported of experiments with a uniform surface roughness only (URA; roughness estimated between 0.01 and 0.02 m; adopted value 0.01m); see [Table 18.](#page-42-0)

Table 18. List of URA Kit Fox experiments for UDM validation

The release is modelled from an area source where observers are released from the upstream edge. The groundlevel cloud is modelled physically more correctly above the source and in the near-field. No additional timeaveraging applied to the calculated concentrations at each arc.

[Table 19](#page-43-0) presents the predictions of MG and VG for the KitFox URA experiments. The individual results are split into continuous and puff experiments. Combined results by stability are also provided. A graphical presentation of the overall MG and VG validation results for the arc-wise concentrations from [Table 19](#page-43-0) is shown i[n Figure 18.](#page-42-1) The overall results can be summarised as follows:

- URA continuous: excellent prediction for both concentration and cloud widths
- URA puff: there is over-prediction for, all results. This is most pronounced for the D weather state, reducing for E and is much improved for F (only a slight over-prediction).

Figure 18. UDM validation statistics for Kit Fox URA experiment

Table 19: UDM values of MG and VG for KitFox URA experiments

4.6.2 Jack Rabbit II experiments

In 2015 and 2016 nine large (up to ~ 10 tonnes) 2-phase chlorine releases were carried out at the US Army Dugway Proving Ground in Utah. These are known as the Jack Rabbit 2 (JR2) tests. Measurements of chlorine concentrations were made out to a distance of 11 km downwind. The 2015 tests were centred in an array of shipping containers (simulating an urban environment) and the 2016 tests were carried out in flat terrain.

A number of models (including Phast) were invited to take part in the Modelling Working Group (MWG), which would simulate the tests using a standardised set of inputs and outputs. Three trials were selected: 1, 6 and 7. Trial 1 from 2015 used the array of shipping containers, while Trials 6 and 7 from 2016 did not. The results of the cross model comparison was published by Mazzola et al²⁴:

Information was provided to try to standardise the input in the models participating in the MWG . The general information on the trials is provided i[n Table 24,](#page-47-0) and more detailed information about the release is shown in [Table 21.](#page-45-0) These represent quite complex releases involving a flashing liquid, with Trials 1 and 6 impinging downwards from 1m while trial 7 impinges downwards at a 45° angle from 1.48m. [Table 24](#page-47-0) attempts to quantify how much of the initial release became vapour, and how much rained out into a pool and was subsequently evaporated. There is clearly much uncertainty around this.

Given the uncertainty around the source term, the Phast modelling of these releases has been made as simple as possible. As the release and pool evaporation are of short duration the results are actually not overly sensitive to however the source is modelled. We have taken the total vapour generation rate from the 'Modified for rainout' and 'Evaporated rainout' sections o[f Table 21](#page-45-0) as a constant vapour flow rate, and modified the duration so that the total mass of vapour released is equal to that as calculated from [Table 21.](#page-45-0) The Phast parameters used are presented in [Table 22](#page-45-1)

Table 20: General information provided to modellers for Jack Rabbit II

Table 21: Detailed release data for Jack Rabbit II

Table 22: Simplified release data used in Phast model

Phast 8.23 was identified in the Mazzola paper as predicting much wider clouds to 20ppm (and 200ppm for Trial 7) than the other models, and also under-predicting concentrations in the far-field. In Phast 8.6 we have introduced the gravity spreading collapse model (GSC) to address these issues (see UDM Theory document for details), and it is therefore useful to update the results.

Calculated MG and VG for the predicted centreline concentrations and widths to 20 ppm are presented in [Table](#page-45-2) [23,](#page-45-2) and the concentrations are also plotted in [Figure 19.](#page-46-0) The equivalent calculations without the new gravity spreading collapse model are presented in [Figure 19](#page-46-0) for comparison. We see a significant improvement in the concentration prediction with GSC activated, with a clear move away from under-prediction. It follows that Phast 8.6 results are significantly improved over Phast 8.23.

The MG/VG analysis can mask the detail of the changes in the calculation, and what we are seeing is similar concentrations in the near to mid-field, but GSC overall maintaining a higher concentration in the far field. An example of this is presented in the concentration vs distance plot i[n Figure 20,](#page-46-1) where the impact of GSC specifically on far field concentrations is more evident.

Table 23: MG and VG values for the plume centreline concentration and width to 20 ppm

Figure 19: MG and VG values plot the plume centreline concentration (without GSC included for comparison)

Figure 20: Concentration vs Distance for Trail 1, with and without GSC

4.7 PHMSA Validation

Phast 8.4 has undergone an external assessment process by the US Department of Transport Pipeline and Hazardous Materials Safety Administration (PHMSA) requiring the comparison of results with a set of field-scale and wind-tunnel tests. This process was previously granted for Phast 6.7 in 2011, with approval sought in 2021 for Phast 8.4. The field-scale experiments have a strong focus on time-varying releases from LNG pool sources, with three of the experiments (Maplin Sands, Burro and Coyote) involving dispersion from an evaporating pool. The validation has been based on the guide to the LNG Model Validation Database by Stewart et al. (Stewart, Coldrick, Gant, & Ivings, 2016)²⁵ and the technical report by Ivings et al. (Ivings, et al., 2016)²⁶. The input data and concentration measurements are chosen as prescribed by version 12 of the modelling dataset Excel spreadsheet supplied by PHMSA.

Results in this section are specifically for Phast 8.6, which includes features not present in 8.4.

4.7.1 Selection of experiments

The Phast model UDM cannot account for obstacles, slopes or fences. Hence model results are only provided for experiments without obstructions, i.e.

- Large-scale LNG experiments: Maplin Sands (27,34,35), Burro (3,7,8,9), Coyote (3,5,6)
- Large-scale Thorney Island Freon/Nitrogen experiments (TI45, TI47)
- Wind-tunnel ground-level area sources: CHRC-A CO2 (16), BA Hamburg SF6 (DA0120, DAT223) and BA-TNO SF6 (TUV01, FLS).

[Table 24](#page-47-0) lists the experiments against which the UDM model has been validated and lists how each model has been modelled by the UDM. The UDM (without source calculations) is invoked in Phast as a 'user-defined source'. This allows us to use exactly the inputs specified in the V12 database. The scenario selection is carried out in the 'Discharge' tab of the 'User-defined source'. The 'Leak' scenario is selected for all field experiments (low momentum horizontal release), while the 'Pool source' scenario is selected for all wind-tunnel experiments (ground-level vapour pool source).

Table 24: List of experiments for PHMSA UDM validation

4.7.2 Analysis & Discussion

The geometric mean (MG) and geometric variance (VG) are probably the most common statistical measures used to assess model performance with experiment and are used in this section to form the basis of the results analysis.

MG and VG values for the experiments assessed are provided i[n Table 25](#page-48-0) an[d Table 26](#page-50-0) for point-wise and arcwise analysis respectively. The PHMSA "Method 2" rolling average approach is used for time averaging where required as this is best aligned the UDM. Concentrations from Phast have been imported into the V12 database and the MG and VG calculated within the database are provided in the tables.

For reference and context, the MG and VG values submitted for the previously submitted Phast 8.4 are also provided, assessed against the sate data-set using the same methodology

MG VG plots for individual experiments and by the experiment groups for both point wise and arc wise calculations are presented in [Figure 21](#page-49-0)[-Figure 24.](#page-51-0)

Table 25: Point-wise MG and VG results

Figure 21: Pointwise MG VG Plot for PHMSA individual experiments (Phast 8.6)

Figure 22: Pointwise MG VG Plot for PHMSA grouped experiments (Phast 8.6)

Table 26: Arc-wise MG and VG results

Figure 23: Arcwise MG VG Plot for PHMSA individual experiments (Phast 8.6)

Figure 24: Arcwise MG VG Plot for PHMSA grouped experiments (Phast 8.6)

4.7.3 Summary

Overall the pattern of Phast 8.6 results is very similar to those submitted for Phast 8.4 a[s Table 25](#page-48-0) an[d Table 26](#page-50-0) show. In the main, there are minor fluctuations to the MG and VG values reported between these releases for most experiments, with the major changes being for Maplin sands and for Thorney Island, where both show large improvements overall.

Maplin Sands, despite the improvement remains significantly under-predicted. The possible causes for this are well known. The spatial (x,y) resolution of the sensors relative to the plumes in the Maplin Sands experiments was not good. Two of the three experiments took place in high wind conditions leading to very narrow plumes which missed most sensors completely. Using the given wind direction, the sensors are 'off-centreline' to an extent that they lie at (or beyond) the edge of the cloud predicted by the UDM. In fact, using the UDM centreline concentration vastly improves alignment with experiment.

The improvement in Thorney Island can be attributed to the inclusion of the Gravity Spreading Collapse model. This restricts the spreading rate when the appropriate conditions are met and subsequently keeps centreline concentrations higher. Only a few of the PHMSA simulations meet the criteria for gravity collapse, the Thorney Island both in that group and the increased concentrations post-collapse are reflected in their MG/VG results which show much reduced under-prediction.

4.8 Conclusions and summary overall UDM statistics for all experiments

For each experimental data set, the summary MG and VG values for point wise and arc wise concentrations (and widths where available) are presented i[n Table 27,](#page-56-0) and centreline concentrations are plotted i[n Figure 25.](#page-55-0) See Sections [4.1.2](#page-17-0) (flashing jets excluding CO₂), [4.2](#page-20-0) (instantaneous releases)[, 4.4](#page-25-0) (CO₂ jets) [4.6](#page-41-1) (Kit Fox) and 4.5 (PHMSA) for a discussion of the results.

Assumptions for UDM AWD runs

The UDM AWD results for PHMSA correspond to the PHMSA specified inputs, with few other required or nondefault inputs set as described in Appendi[x A.5.](#page-75-0)

The UDM AWD results for the Kit Fox URA experiments are based on the pool-source assumption including additional time averaging, i.e. the results correspond to those shown i[n Figure 18.](#page-42-1)

Conclusions

- 1. Data sets not involving time-varying source terms
	- a. The performance of the UDM against the Prairie Grass, Desert Tortoise, BP, Shell, EEC and Kitfox continuous experiments is good or excellent.
	- b. The performance of the UDM against the aerosol releases of Desert Tortoise, EEC and FLADIS, in which both heavy and jet entrainment dominates, is reasonable.
	- c. The performance against the CO2 pressurised releases, including the COSHER buried pipelines, is excellent
	- d. The performance against the Kit Fox continuous experiments is excellent.
	- e. Results in Phast 8.6 have not significantly changed from Phast 8.4, except for Goldfish which has improved due to the Gravity Spreading Collapse model
- 2. Instantaneous and short duration (URA puff) experiments
	- a. Thorney Island results are good, and consistent with earlier versions.
	- b. The new UDM AWD method produces overall lower MG values (more conservative concentration predictions) than the FDC method.
	- c. Results are best for Stability F (with a slight over-prediction), and worst for Stability D (a significant under-prediction).
- 3. Buried pipeline experiments (COSHER)
	- a. Performance is excellent using the new modelling introduced in Phast / Safeti 8.9, although the COSHER 1 experiment is under-predicted at low concentration levels
	- b. With only 2 experiments, there is a worrying lack of suitable validation data
- 4. Experiments involving dispersion from pool:
	- a. All pool-based dispersion (Burro, Maplin Sands, Coyote) has been redone since 8.4 using different data and methodology as prescribed by PHMSA. The results for 8.6 remain in line with those for 8.4.
	- b. The results for Burro and Coyote (short) remain good, with only minor variations in statistics since 8.4 Maplin Sands and Thorney island have improved significantly, although for Maplin Sands there remains a large under-prediction (using fixed and widely spaced crosswind sensor locations for narrow plumes can lead to gross under-estimation of concentrations).

- 5. Wind-tunnel experiments
	- a. CHRC, BA-TNO and BA-Hamburg simulations all under-estimate concentrations, However predictions are significantly better than those obtained for Phast 6.7 (Witlox et al, [2](#page-6-0)011)²
	- b. All wind-tunnel experiments were simulated at field scale rather than wind-tunnel scale using input provided by PHMSA. It is possible that scaling of these releases has affected results^{xv}

 x^v Wind-tunnel scale was recommended for the simulations, but this is not currently possible in the UDM due to limitations

Figure 25. Summary MG and VG values for arcwise maximum concentration

Table 27: Summary MG and VG values from Phast 8.6 for concentration for all experimental data setsxvi

Widths used are Hanna (Prairie Grass except 8 and 17, Goldfish, Desert Tortoise 3 and 4, URA puff, URA continuous), SMEDIS (EEC, FLADIS, Desert Tortoise 1 and 2) and max width to concentration (JR2). In line with the most recent PHMSA MEP, only pointwise concentrations are compared for the PHMSA set of experiments.

 xvi Crosswind experiments not included as point-wise and arc-wise calculations of MG/VG are not used to assess them

APPENDICES

Appendix A. Notes on Input data for validation runs

A.1 **Continuous (excluding CO2)**

1) The data for PG8 and PG17 were provided from SMEDIS^{[11](#page-10-0)}

2) The dispersing surface temperature was set to the temperature at the reference height.

1) Data for DT1 and DT2 are taken from SMEDIS^{[11](#page-10-0)} who provided post flash data. DT3 and DT4 post-flash velocity and liquid fraction are calculated using DISC / ATEX and the conservation of momentum method.

2) All the cases predict rainout. The pool segment giving the largest vaporisation rate during the release was selected for version comparison

3) Bund temperature and surface temperature taken from Hanna's¹⁰ report who specifies a soil temperature.

1) These data were provided as part of the SMEDIS^{[11](#page-10-0)} project.

2) Droplet size was calculated using Phastxvii

3) The reference height for temperature was set to the reference height for wind speed.

4) The surface temperature was set to the ambient temperature at the reference height.

5) To bring the predictions in line with the SMEDIS results, the cut-off evaporation rate parameter was changed to 0.1 kg/s.

^{xvii} Except for EEC170, where no pre-release conditions were available. Value assumed to be 40 μm, in line with other experiments; see Section 4.1.1. EEC170 also has no arc-wise maximum concentration data.

1) These data were provided as part of the SMEDIS project

- 2) For FLADIS16 the stability class was given as being D/E. This option is not available within the UDM, hence stability class E was taken as a conservative option.
- 3) The reference height for temperature was set equal to the reference height for windspeed.
- 4) The surface temperature was set to the temperature at the reference height.

1) Goldfish input data were obtained from McFarlane et al 12

2) The surface temperature was set to the temperature at the reference height.

^{xviii} Surface temperature assumed same value

Table 28. UDM input data for Thorney Island experiments (continuous)

- 1) The release height is given as 0m, with diameter 2m, but the geometry of the release was complicated: a vertical pipe with a 2m diameter plate 0.5m above the surface to ensure low vertical momentum. It is not obvious how this should be modelled in Phast. We have chosen a very low momentum horizontal jet, with horizontal velocity *u* equal to the calculated source exit velocity assuming a pipe of diameter D_{source} = 2 m: *u* $= Q / (A_{\rho}$. Here Q is the release rate (kg/s), A is the source area (= 0.25 π D_{source}²) and ρ the vapour density of the Freon-12 / N_2 mixture. Receptor height has likewise been assumed to be ground level.
- 2) For TI45, the actual stability class is E-F, whereas in Phast one must choose either E or F. We have chosen F, but using F does not make very much difference with E especially down to the 1% or so concentration level.

1) These experiments were not included in the PHMSA dataset.

2) We have used the MDA quoted release height of zero (unlike for the 7.1 simulation for the LNG experiments; ground-level spill)

3) Relative humidity for MSP42 and MSP43 were not included in the MDA

4) The cases are modelled as continuous spills at minimum release velocity (0.1 m/s) and with the maximum droplet diameter (0.01m)

A.2 **Instantaneous**

1) The experimental concentration data was multiplied throughout by the mole fraction of Freon in the release so that a direct comparison could be made with the UDM results.

2) The assumption of 0 J/kg for the expansion energy is a reasonable assumption as this is an unpressurised release.

3) The dispersing surface temperature was set to the temperature at the reference height.
4) Mole fraction of Freon-12 was calculated from the molecular weight for each experimen

4) Mole fraction of Freon-12 was calculated from the molecular weight for each experiment given in the MDA, but not used. Consistent with previous versions of this report (but unlike the Thorney Island continuous experiments) the material used is pure Freon-12 (CAS 75071-8).

A.3 **Pressurised CO² releases (BP and Shell experiments)**

Key Phast discharge and dispersion input data

[Table](#page-65-0) 29 summarises the key BP experimental data required as input to the Phast discharge models DISC (steady-state or initial rate) and TVDI (time-varying releases) and the UDM dispersion model. In this table the values of the storage pressure and the storage temperature are taken at the discharge end of the vessel (upstream of the pipework), with mean values during the release applied for the steady-state liquid releases and with initial values applied for the transient vapour releases. The ambient data were measured upwind of the release and mean values are adopted for these data during the release. This is with the exception of the wind-speed measurement taken 40m downwind of the release at 1.65m above the pad. Since this measurement was disturbed by the $CO₂$ jet, the value listed in [Table](#page-65-0) 29 corresponds to the mean value prior to the release.

Table 29. Experimental conditions for BP CO² tests

Table 30. Experimental conditions for Shell CO² tests

Likewise [Table 30](#page-65-1) summarises the key Shell experimental data required as input to the Phast models. In this table the values of the storage pressure and the storage temperature are taken at the discharge end of the vessel (upstream of the pipework) and the nozzle pressure/temperature are taken along the nozzle, with mean values during the release applied for the steady-state releases and with initial values applied for the transient releases. The wind speed data were taken from tower A [20m west (behind) and 5 meter south of release point] at 10 meter height (averaged prior to release) given anomalies observed at other measurement locations.

Furthermore, based on an analysis of the experimentally observed vertical wind-speed profiles a surface roughness of 0.1m and a stability class of D was assumed for all (BP and Shell) tests. Finally with respect to the wind direction it is noted that the release direction corresponds to 270°.

MDA format

Data for the BP and Shell $CO₂$ experiments have been included in the format of the MDA database by Witlox^{27,28} and these data are given b[y Table 31](#page-67-0) an[d Table 32.](#page-69-0)

The following further additional notes are given for [Table 31](#page-67-0) (BP tests):

Tests 1-3, 6, 11 were truly steady-state releases where the pressure was kept constant using a padding gas and therefore a reliable estimate of flow rate was obtained.

For the steady-state liquid tests the mean values of pressure and temperature at the vessel outlet (discharge end of the vessel) during the release are specified, while for the time-varying hot tests initial values are specified. Thus the specified exit gauge pressure may be too high for test 5, since for this test the pressure was not kept constant and frictional effects upstream of the orifice were important.

Tests 8, 8R, 9 were time-dependent releases, where the flow rate was accurately measured. The pressures listed in the table are initial pressures, while the reported flow rates in the table are averaged flow rates over the first twenty seconds.

The un-averaged peak concentrations have been based on ALL sensors, and any possible faulty sensors have not been excluded. The averaged maximum concentrations are based on 11-second averaged concentrations excluding faulty sensors. These observed estimates may be somewhat conservative since the maximum value over all times of the11-second averaged has been applied. Furthermore no further analysis has been carried out (e.g. via spline fitting of the measured values to obtain a better fit of the crosswind concentration profile and a better estimate of the maximum concentration) to further refine this maximum value.

The following further additional notes are given for [Table 32](#page-69-0) (Shell tests):

Tests 3,5,11 were truly steady-state releases where the pressure was kept constant using a padding gas. Tests 1, 2, 4 were time-varying releases from a vessel initially fully filled with pressurized liquid. Tests 14 and 16 were time-varying releases from a vessel initially filled with pressurized vapour (at supercritical temperature).

For the 1" tests 5 and 2 there was a significant pressure drop along the pipework between the vessel outlet and the nozzle. Therefore for the steady-state liquid tests mean nozzle values during the release are specified, while for the time-varying liquid tests initial nozzle values are specified. For the $\frac{1}{2}$ " vapour tests 14 and16 the initial vessel outlet values are specified.

Servomex and Draeger sensors were only positioned at limited locations and therefore these have not been used. $O₂$ sensors showed an erroneous drop with time in the near-field, and therefore averaged values for the O_2 sensors have not been used. Thus the maximum value of the peak values for the O_2 sensors located at a given downstream distance have been used to determine the measured peak concentration at a given downstream distance. No further analysis has been carried out (e.g. via spline fitting of the measured values to obtain a better fit of the crosswind concentration profile and a better estimate of the maximum concentration) to further refine this maximum value.

MDA INPUT VARIABLE									MEANING INPUT VARIABLE	REFERENCE / ADDITIONAL NOTE
BP DF1 C02 pressurised field releases, SpadeAdam									Name of field experiments	
Carbon Dioxide									Chemical released	
CO ₂									3-char. abbreviation of chemical	
9									number of trials included in MDA	
CO2BP1	CO2BP2	CO2BP3	C02BP5	CO2BP6	CO2BP11	CO2BP8	CO2BPR	CO2BP9	: time zone designation : trial ID	??? To apply GMT time tests: steady liquid (1,2,3,5,6,11), transient vapour (8,8R,9)
1	21	28	16	7	20	17	22	16	: day	Advantica report - Appendix A,B,C,E,F,L,H,I,J
11	$11\,$	11	12	12	11	$11\,$	11	11	: month	Advantica report - Appendix A,B,C,E,F,L,H,I,J
2006	2006	2006	2006	2006	2006	2006	2006	2006	: year	Advantica report - Appendix A,B,C,E,F,L,H,I,J
12	16	14	13	16	16	15	14	14	: hour	Advantica report - Appendix A,B,C,E,F,L,H,I,J
39	3	50	28	$\overline{2}$	30	$20\,$	15	Ω	: minute	Advantica report - Appendix A,B,C,E,F,L,H,I,J
44.01	44.01	44.01	44.01	44.01	44.01	44.01	44.01	44.01	: mol. weight (g/mole)	Property as in MDA KitFox for CO2
186.25 154749	186.25 154749	186.25 154749	186.25 154749	186.25 154749	186.25 154749	186.25 154749	186.25 154749	186.25 154749	: normal boiling point (K) : latent heat of evaporation (J/kg) at 20C	Property as in MDA KitFox for CO2
839.3	839.3	839.3	839.3	839.3	839.3	839.3	839.3	839.3	: specific heat - vapor (J/kg-K) at 20C	Property as in MDA KitFox for CO2 Property as in MDA KitFox for CO2
4118.8	4118.8	4118.8	4118.8	4118.8	4118.8	4118.8	4118.8	4118.8	: specific heat - liquid (J/kg-K) at 20C	Property as in MDA KitFox for CO2
773.3	773.3	773.3	773.3	773.3	773.3	773.3	773.3	773.3	: density of liquid (kg/m**3) at 20C	Property as in MDA KitFox for CO2
-1	$^{\rm -1}$	-1	-1	-1	-1	-1	$^{\circ}1$	-1	: coefficient A for vapor pressure equation	?? Suggest use DIPPR formula (vapour/solid vapour pressure)
$\mathbf 0$	$\mathbf 0$	0	$\bf 0$	0	0	0	$\mathbf 0$	0	: coefficient B for vapor pressure equation	?? Suggest use DIPPR formula (vapour/solid vapour pressure)
103.40	155.50	133.50	157.68	156.72	82.03	157.76	148.72	154.16	exit gauge pressure (bar)	mean (steady tests) or initial (transient tests) at vessel outlet
278.15	280.99	284.171	282.27	282.6252	290.59	420.27	422.52	342.32	: source temperature (K)	mean (steady tests) or initial (transient tests) at vessel outlet
1.19E-02	1.19E-02	1.19E-02	2.56E-02	6.46E-03	1.19E-02	1.19E-02	1.19E-02	1.19E-02	source diameter (m)	
1.1 HJ	1.1 HJ	1.1 HJ	$1.1\,$ HJ	1.1 HJ	1.1 HJ	1.1 HJ	1.1 HJ	1.1 HJ	: source elevation (m) : source type (IR,HJ,AS,EP)	Horizontal jet (HJ)
	L	L	L	L	L	G	G	G	: source phase (L,C,G)	Liquid (L) or gas (G)
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: source containment diameter (m)	
8.2	11.41	9.987826	41.17	$3.5\,$	7.12	4.07	3.8	6.05	: spill/evaporation rate (kg/s)	8, 8R, 9 are time-varying releases (averaged rate taken over first 20s)
59	59	60	40	120	58	120	132	179	: spill duration (s)	8, 8R, 9 are time-varying releases
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: total released (kg)	
1.00E+06	1.00E+06	1.00E+06	1.00E+06	1.00E+06	1.00E+06	1.00E+06	1.00E+06	1.00E+06	: initial concentration (ppm)	
0.9994	0.9582	0.9725	0.9854	0.9384	0.9602	0.95799	0.9571	0.9589	: ambient pressure (bar)	Advantica report - Appendix A,B,C,E,F,L,H,I,J (except Test 8 - Leng)
74.4 287.35	96 280.65	95.8 283.75	96.7 278.95	100 279.25	94 284.75	100 284.34	100 284.25	99.9 281.35	: relative humidity (%) : ambient temperature #1-lower (K)	Advantica report - Appendix A,B,C,E,F,L,H,I,J Advantica report - Appendix A,B,C,E,F,L,H,I,J (except Test 8 - Leng)
0	0	0	$\mathsf{O}\xspace$	0	$\mathsf{O}\xspace$	0	0		: measurement height for temperature #1 (m)	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: ambient temperature #2-upper (K)	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: measurement height for temperature #2 (m)	
285.35	278.65	281.75	276.95	277.25	282.75	282.34	282.25	279.35	: soil temperature (K)	Following BP advice, assumed to be 2 degrees lower than ambient
$\mathbf{1}$	1	1	1	$\mathbf{1}$	$\mathbf{1}$	$\mathbf 1$	1		soil moisture (1:dry,2:moist,3:water)	
4	3.44	3.37	5.13	2.2	5.99	4.71	0.76	4.04	: wind speed (m/s)	Windspeed at 40m distance; average value before start release
1.65	1.65	1.65	1.65	1.65	1.65	1.65	1.65	1.65	: measurement height for wind speed (m)	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: domain-avg wind speed (m/s)	
-99.9 -99.9	-99.9 -99.9	-99.9 -99.9	-99.9 -99.9	-99.9 -99.9	-99.9 -99.9	-99.9 -99.9	-99.9 -99.9	-99.9 -99.9	domain-avg sigma-u (m/s) domain-avg sigma-theta (deg)	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: measurement ht for domain-avg wind data (m)	
	?	?	3	?	P	?	3	3	: averaging time for wind and temperature data (s)	to check
0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	: roughness length z0 (m)	presumed
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: friction velocity u-star (m/s)	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: bowen ratio estimate	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: inverse Monin-Obukhov length (1/m)	
$\overline{4}$	$\overline{?}$ 4	3 4	3 $\overline{4}$? 4	$\overline{}$ 4	P 4	3 4	3	: cloud cover (%) : Pasquill-Gifford stability class (A=1;D=4;F=6)	??? To check Assumed D
	?	?	3	?	ļ?	?	?	3	: latitude (deg)	??? To apply SpadeAdam location
	$\overline{?}$	3	?	?	$\overline{?}$?	3	3	: longitude (deg)	PPP To apply SpadeAdam location
1	1	$\mathbf{1}$	$\mathbf{1}$	$\mathbf{1}$	$\mathbf 1$	$\mathbf{1}$	1		: averaging time for peak concentration (s)	
11	$11\,$	11	$11\,$	11	11	11	$11\,$	11	: averaging time for averaged concentration (s)	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	concentration of interest for modeling (ppm)	
$\mathbf{1}$	$\mathbf 1$	$\mathbf{1}$	$\mathbf 1$	$\mathbf{1}$	$\mathbf 1$	$\mathbf{1}$	$\mathbf 1$	-1	: suggested receptor height for modeling (m)	
$\sqrt{4}$ 5	4 5	4 5	$\overline{4}$ 5	4 5	$\overline{4}$ 5	4 5	4 5	4 5	: number of distances downwind	
10	10	10	10	10	10	10	10	10	distance downwind (m) distance downwind (m)	
15	15	15	15	15	15	15	15	15	distance downwind (m)	
20	20	20	20	20	20	20	20	20	distance downwind (m)	
40	40	40	40	40	40	40	40	40	distance downwind (m)	
60	60	60	60	60	60	60	60	60	distance downwind (m)	
80	80	80	80	80	80	80	80	80	distance downwind (m)	
22.22	27.98	50.05779	-99.9	21.99	21.88	9.185435	8.813	15.58	: max. conc. (mol %) based on tpeak	All sensors; Original MDA uses ppm instead of mol%
7.10	13.69	16.054	-99.9	8.5271	9.19	4.061425	4.0978	7.16	: max. conc. (mol %) based on tpeak	All sensors
3.10 5.32	9.02	9.598 6.4985	-99.9 14.244	4.7239 4.5924	5.53	2.987029 2.950585	2.7901 2.391	5.12 3.68	: max. conc. (mol %) based on tpeak : max. conc. (mol %) based on tpeak	All sensors All Sensors
-99.9	6.79 6.12	7.143774	15.496	5.3699	4.02 4.82	2.563892	4.3929	4.99	: max. conc. (mol %) based on tpeak	All sensors
-99.9	-99.9	5.0102	8.8944	-99.9	-99.9	-99.9	-99.9	-99.9	: max. conc. (mol %) based on tpeak	All sensors
-99.9	-99.9	2.774052	6.3711	-99.9	-99.9	-99.9	-99.9	-99.9	: max. conc. (mol %) based on tpeak	All sensors
21.14	27.46918	37.1426	-99.9		20.77245 21.146655	8.37158	7.705936	15.03	: max. conc. (mol %) based on tavg	Excluding non-trusted sensors
6.23	12.93045	15.167	-99.9	7.978891	8.3783636	3.492025	3.287882	6.38	: max. conc. (mol %) based on tavg	Excluding non-trusted sensors
2.27	8.2248	8.8559	-99.9		4.200045 4.1569909	2.119683	2.215382	4.29	: max. conc. (mol %) based on tavg	Excluding non-trusted sensors
4.53	5.685891	5.905018	13.86173	3.083936	3.0273545	1.99604	1.712187	2.90	: max. conc. (mol %) based on tavg	Excluding non-trusted sensors
-99.9	3.582927	3.220491	8.615255	2.2071	0.9010455	0.914108	1.860149	1.81	: max. conc. (mol %) based on tavg	Excluding non-trusted sensors
-99.9 -99.9	-99.9 -99.9	3.119291 1.58873	5.410327 4.241636	-99.9 -99.9	-99.9 -99.9	-99.9 -99.9	-99.9 -99.9	-99.9 -99.9	: max. conc. (mol %) based on tavg : max. conc. (mol %) based on tavg	Excluding non-trusted sensors Excluding non-trusted sensors
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: sigma-y (m) based on time-summed concentration	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: sigma-y (m) based on time-summed concentration	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: sigma-y (m) based on time-summed concentration	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: sigma-y (m) based on time-summed concentration	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: sigma-y (m) based on time-summed concentration	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: sigma-y (m) based on time-summed concentration	
-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	-99.9	: sigma-y (m) based on time-summed concentration	

Table 31. MDA data for BP DF1 CO2 experiments (input and measured data)

Table 32. MDA data for Shell CO² experiments (input and measured data)

A.4 **Finite-duration dispersion (Kit Fox experiments)**

The input data for the Kit Fox experiments are given below as taken from the MDA database from Hanna and Chang (1999)^{[23](#page-41-2)}.

A.5 **PHMSA Validation Cases**

LNG Experiments

The main assumptions for the LNG releases are outlined below:

- LNG is modelled as pure methane. This is in line with our recommendation for multi-component releases in Phast 6.7, since methane is the main component for all LNG releases. The LNG Model Validation Database also states this is generally an acceptable approach to model LNG vapour from evaporating pools.
- For these experiments, the methane was released from an elevated height with a very low momentum. This results in close to 100% rainout almost immediately.
- Coyote and Burro the spills were into a water basin, and we specify the "shallow open water" pool surface type. This has a minimum pool depth of 1 mm, and allows for ice formation underneath the pool. Given its offshore location, and in the absence of evidence to the contrary, we have run Maplin Sands using "deep open water" which does not allow ice formation. For Burro and Coyote the subsequent dispersion was over land, whereas the substrate is water for Maplin Sands.
- "Short" averaging time releases use t_{av} = 18.75s (equivalent to instantaneous maximum concentration when accounting for wind meander). "Long" averaging time releases use the specified value of t_{av} and use a timecentred rolling average calculation over that period to calculate concentrations. This corresponds to "Method 2" in the V12 database guide.
- For Coyote, custom processing within Phast and post-processing of exported results has been performed in order to remove the post-ignition data from the calculated time series..
- Phast normally uses a post-processing correction to unaveraged results (i.e. generated using $t_{av}=18.75$ s) to account for different averaging times. This is done for performance reasons when users are interested in multiple averaging times. Here however for maximum accuracy we run all calculations at the desired averaging time. This applies to all experiments, not just LNG.
- We have assumed low release velocity (0.1 m/s) and the maximum permissible droplet size (1 cm) in all cases. Results are insensitive to changes in these inputs over realistic ranges.

The Phast default parameters should be sufficient for all other settings. A comprehensive set of input data for the LNG experiments is provided i[n Table 33.](#page-76-0)

Table 33: UDM Input Data for all PHMSA LNG experiments

Thorney Island Continuous Experiments

The geometry of the release was complicated: a vertical pipe releasing gas into a 2m diameter plate 0.5m above the surface to ensure low vertical momentum. The arrangement is shown in [Figure 26,](#page-77-0) with the images taken from McQuaid & Roebuck (McQuaid & Roebuck, 1985)²⁹.

Fig. 22.2 Outlet from the gas supply duct at the release point

Figure 26: Thorney Island Source for continuous release experiments.

It is not obvious how such a cylindrical source should be modelled in Phast. This is in-effect is a low momentum 'cylindrical wall' gas source, released in all directions before being dispersed downwind. Phast requires the provision of a flow rate and a velocity, from which a (planar) release area will be calculated. We have chosen a very low momentum horizontal jet, with horizontal velocity u equal to the calculated source exit velocity assuming a pipe of diameter $D_{source} = 2 m$ and plate height $h = 0.5 m$

$$
u=\frac{Q}{A\rho_v}=\frac{Q}{\pi\rho_v}
$$

Here Q is the release rate (kg/s), A is the source area (= $\pi D_{source}h$) and pv the vapour density of the Freon-12 / N2 mixture. This gives an equivalent release source with the correct velocity and flow rate, although the full mass flux is initially directed in a single direction. The height associated with the release is selected to be 0.25 m, half the height of the diverting plate.

While the overall flow rate and exit velocity are accurately represented in Phast, the directionality at the source is not: net horizontal momentum for the actual release is zero, and this could affect near-field concentrations

For TI45, the actual stability class is E-F, whereas in Phast one must choose either E or F. We have chosen F, this does not affect results significantly down to the 1% or so concentration level.

All measurements are based on an averaging time of 30s. The input data used for the Thorney Island experiments are presented i[n Table 34.](#page-78-0)

Table 34: UDM input data for Thorney Island (continuous) experiments

Wind Tunnel Experiments

These wind-tunnel experiments involved isothermal releases. They corresponded to $CO₂$ (CHRC-A) and SF $₆$ (BA-Hamburg,</sub> BA-TNO) vapour area sources at ground level. Only the unobstructed experiments have been modelled.

All the experiments have been modelled at field scale rather than at the experimental scale. The UDM default atmospheric wind-speed profile (a function of vertical height, stability class and surface roughness) is appropriate for outdoor conditions but may not be appropriate for the wind tunnel. The wind profile exponent is calculated for a fixed geometric mean height for the boundary layer of 32.6m. Instead one should ideally use a best power-law fit to the experimentally observed windspeed profile, but currently Phast does not support the direct input of a wind exponent. Therefore we have used the scaled data in our simulations. The UDM passive dispersion coefficients σ_y , σ_z (as function of downwind distance, stability class, averaging time, etc.) are based on typical outdoor ambient turbulence and may again not be valid for wind tunnel conditions (although this may be less of an issue for neutral conditions).

Thus overall one needs to be very careful applying the standard UDM model to wind tunnel conditions, particularly with reference to establishing the ambient conditions (wind speed, turbulence) inside the wind-tunnel. Since modification of these ambient conditions is not currently possible by the Phast user, we have therefore selected to model the full-scale comparison only.

In each case, the release source is at ground level over a relatively wide field-scale area with low gas velocity. Such releases can be specified in Phast as a 'pool source (radius)' on the 'user-defined source' window representing the release. The user needs to specify the flow rate, temperature and radius corresponding to the given source area, with the release velocity calculated from these values.

The input data used for the wind tunnel experiments are presented i[n Table 35.](#page-80-0) The largest changes in the input data from the previous V11 database are related to the BA-Hamburg experiments, and largely related to uncertainties regarding the obstructed experiments. The changes that impact the unobstructed cases are:

- Clarification of the release flow rate and the source/ambient temperatures associated with the experiments.
- A recommendation for modellers to select the appropriate surface roughness which gives closest agreement with the vertical velocity and turbulence intensity profiles published by Marotzke and presented in the V12 database guide (Stewart, Coldrick, Gant, & Ivings, 2016).

The Marotzke velocity profile has been fitted to the UDM power law formulation to give a best fit roughness of 0.0039 m, which has been used for both BA-Hamburg experiments. This is within the stated range of 0.0055m \pm 0.0045m for the equivalent field scale surface roughness.

Table 35: UDM input data for wind tunnel experiments

Appendix B. Definition of cloud width

The cloud width for a continuous release is calculated according to the availability and definition of the experimental cloud width:

1. No experimental cloud width data

In the cases where no experimental data is available the UDM effective cloud half width is plotted. This is defined as follows (see UDM theory manual for further details)

$$
W_{\text{eff}} = \frac{1}{c(x,0,z)} \int_{0}^{\infty} c(x,y,z) dy = \int_{0}^{\infty} F_h(y) dy = \Gamma(1+\frac{1}{m}) R_y(x)
$$
 (11)

2. SMEDIS data

The cloud width b (m) for SMEDIS^{[11](#page-10-0)}output is defined by

$$
b^{2} = \frac{\int_{0}^{\infty} y^{2} c(x, y, z) dy}{\int_{0}^{\infty} c(x, y, z) dy} = \frac{\int_{0}^{\infty} y^{2} F_{h}(y) dy}{\int_{0}^{\infty} F_{h}(y) dy} = \frac{\Gamma(\frac{3}{m})}{\Gamma(\frac{1}{m})} R_{y}(x)^{2}
$$
(12)

and therefore

$$
b = \sqrt{\frac{\Gamma(\frac{3}{m})}{\Gamma(\frac{1}{m})}} R_y(x)
$$
 (13)

3. Hanna's Data

Hanna's^{[10](#page-10-1)} cloud width is defined as the lateral distance at which the cloud concentration has fallen to a factor $e^{-0.5}$ times the centreline concentration:

$$
\frac{c(x,b,z)}{c(x,0,z)} = e^{-0.5}
$$
 (14)

From this definition the following relationship may be defined:

$$
c(x, b, z) = c_o(x) F_h(b) = c_o(x) \exp\left[-\left(\frac{b}{R_y(x)}\right)^m\right]
$$
 (15)

hence from the given definition

$$
\exp\left[-\left(\frac{b}{a_2(x)}\right)^m\right] = \exp(-0.5) \quad ; \quad b = \frac{R_y(x)}{2^{1/m}} = 2^{\frac{1}{2} - \frac{1}{m}} \sigma_y \tag{16}
$$

4. PHMSA data

For the Burro and Coyote experiments, the UDM cloud width has been calculated in line with the LNG guideline by Coldrick et [al](#page-6-0)³. Thus the width is calculated using the Pasquill definition of cloud width, b_{PASQUILL}. See the UDM theory manual for the UDM concentration profile, which expresses the concentration $c(x,y,z)$ as a function of downwind distance x, crosswind distance y and vertical height z. By insertion of this profile into the formula for the cloud width, the UDM cloud width has been evaluated (m = vertical cross-wind concentration profile exponent, $R_y = UDM$ cloud crosswind radius, Γ = Gamma function):

$$
b_{PASQUILL} = \sqrt{\int_{0}^{\infty} y^2 c(x, y, z) dy \left[\int_{0}^{\infty} y c(x, y, z) dy \right]^2} = R_y(x) \sqrt{\left[\frac{\Gamma(\frac{3}{m})}{\Gamma(\frac{1}{m})} - \frac{\Gamma(\frac{2}{m})}{\Gamma(\frac{1}{m})} \right]}
$$
(17)

Comparison of cloud widths

[Figure 27](#page-83-0) plots each of the four above definitions for cloud width (as a proportion to RADY), as a function of the exponent m in the crosswind conentration profile. According to the UDM theory manual, m is a function of the density ratio r = $(\rho_{\text{cld}} - \rho_a)/\rho_a$ with m=2 for r=0 and m \rightarrow 50 for values 5 larger than 5. Thus for a heavy gas release, m will typically vary from m=50 (top-hat profile) in the near-field to m=2 (Gaussian profile) in the far-field.

- As $m \rightarrow 50$ (typically in the near-field), the Hanna width becomes close to the effective cloud width, while the SMEDIS and PHMSA definitions become smaller.
- As $m \to 2$ (downwind distance $x \to \infty$) the definitions by Hanna, SMEDIS and PHMSA become identical. Thus for experimental datapoints sufficiently downwind, all the latter three defintions lead to identical result.

Time-varying release

All the above formulas are applicable to continuous releases. For the datasets currently in the experimental database effects of time-varying dispersion are only applicable to the Kit Fox experiments (finite-duration releases; MDA Hanna's definition of cloud width b; along-wind diffusion effects relevant) for to the experimennts involving pools (Burro, Coyote, Maplin Sands; PHMSA definition of cloud width b; along-wind diffusion effects not relevant).

Hanna's equation [\(14](#page-81-0)) can also be applied for time-varying releases, where for validation purposes (to evaluate MG, VG) the maximum value of the cloud width b over all times is adopted.

The SMEDIS and PHMSA integral definitions of cloud width given by Equation[s \(12](#page-81-1)) an[d \(17](#page-82-0)) could be applied in general for time-varying releases, but this would require an evaluation of the integrals and again a maximum value of y over all times could be adopted. However if one would ignore effects of along-wind diffusion and observer mass correction, one can again use the analytical expression[s \(13](#page-81-2)) an[d \(17](#page-82-0)) in terms or R^y and m to evaluate the cloud width b, where again for validation purposes (to evaluate MG, VG) the maximum value of the cloud width b over all times is adopted.

Appendix C. Chronological comparison of the performance of the UDM

The tables below present a statistical comparison of the UDM predictions with the measured experimental data for different releases of the UDM, from Version 5.2 to the present release.

Phast 6.0 considerably improved predictions over earlier versions. Since 6.0, the performance of the UDM has been relatively stable. Changes for Phast 6.7 results reflect the first PHMSA validation process (using the v11 database) and show differences for LNG and related experiments. The most significant changes occurred for v8.0 with the introduction of "observer" based dispersion modelling and AWD. Most recently, the Goldfish simulations for v8.4 have been updated to use purely McFarlane experimental data.

Another trend apparent from the table is the gradual extension of the experimental database to include additional datasets. The Coyote and Maplin Sands LPG experiments were added for v6.7; Thorney Island continuous were added for v6.7; BP and Shell CO₂ were added for v8.0. This trend is likely to continue. From v8.4, all cases are available from DNV as Phast study files.

From Phast 8.4, the cases comprising the PHMSA validation set have been introduced in their entirety. The PHMSA v12 validation database has introduced a more detailed data set than previously including expanded point-wise concentrations (including Maplin Sands and Thorney Island which were previously arc-wise only), refined sensor coordinates and removal of post-ignition data for the Coyote experiments. Furthermore the arc-wise calculation for PHMSA is based on a sub-set of the observed and predicted concentrations at the sensor locations on an arc (as opposed to arc-wise predictions being the centre-line concentration at the arc). Making direct comparison between the current and previous mean and variance values for the PHMSA cases is difficult given these changes to the data set and the calculation method. As such from Phast 8.4 the PHMSA set as calculated by the PHMSA methodology will be presented. Previous values which were calculated using a sub-set of the current PHMSA data (e.g Maplin Sands, Burro, Coyote) will not be carried forward for comparison.

		Concentration		Half Width	
Series	Phast /Safeti version	Mean	Variance	Mean	Variance
Prairie Grass ¹⁹	6.0	0.91	1.67	0.80	1.19
	6.42	0.91	1.67	0.88	1.19
	6.7	0.93	1.79	0.88	1.19
	8.0	0.94	1.67	0.89	1.19
	8.4	0.98	1.69	0.88	1.22
	8.6	0.95	1.69	0.90	1.21
	8.9	0.95	1.69	0.90	1.21
Desert Tortoise ²⁰	6.0	1.00	1.21	1.00	1.06
	6.42	1.01	1.20	1.06	1.07
	6.7	0.98	1.20	1.06	1.07
	8.0	1.01	1.21	1.03	1.06
	8.4	1.01	1.21	1.04	1.05

¹⁹ Hanna values only. PG8 and 17 width from SMEDIS omitted

l

²⁰ SMEDIS values only (DT1 and 2), Hanna omitted

Validation | Unified Dispersion Model version 8.6 |

Table 36. Chronological performance for MG/VG values

		Pointwise	
Series	Version MG		VG

Validation | Unified Dispersion Model version 8.6 | 21 Changes reflect corrections to the validation data used for this experiment set

 \overline{a}

Table 37: Chronological list (starting at v8.4) for the PHMSA validation set

NOMENCLATURE

About DNV

We are the independent expert in risk management and quality assurance. Driven by our purpose, to safeguard life, property and the environment, we empower our customers and their stakeholders with facts and reliable insights so that critical decisions can be made with confidence. As a trusted voice for many of the world's most successful organizations, we use our knowledge to advance safety and performance, set industry benchmarks, and inspire and invent solutions to tackle global transformations.

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